

Simscape™ Electrical™ Release Notes



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Simscape™ Electrical™ Release Notes

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R2020a

Version: 7.3

New Features

Bug Fixes

Simscape Electrical

Converters and Choppers Blocks: Select averaged switch option for switching device type

These blocks now support an additional type of switching device:

- Bidirectional DC-DC Converter
- Boost Converter
- Buck Converter
- Buck-Boost Converter
- Converter (Three-Phase)
- Four-Quadrant Chopper
- One-Quadrant Chopper
- Three-Level Converter (Three-Phase)
- Two-Quadrant Chopper

To enable the new switching device, set **Switching devices** parameter to Averaged Switch.

Load-Flow Analyzer App: Generate, visualize, sort, tune, and export steady-state voltage and power data for three-phase AC power transmission systems

The **Load-Flow Analyzer** app performs a power-flow, or load-flow, analysis for a three-phase AC electrical power transmission system that you model and configure for analysis using Simscape Electrical. The app generates two tables. One of the tables contains data for the network nodes, as represented by Busbar, Load Flow Source, synchronous machine, induction machine, and three-phase load blocks. The other table contains data for the network connections, as represented by transmission lines, cable, and transformer blocks. When you open the tool, the tables are preloaded with the specified parameter values for the relevant blocks in the current or specified model. After you run the power-flow analysis, the tables also display the steady-state voltage magnitudes, voltage phase angles, active power, and reactive power for the node and connection blocks.

The **Load-Flow Analyzer** app allows you to:

- Run a power-flow analysis.
- Highlight and update inputs for parameters in the Nodes table for busbar, load flow source, synchronous machine, induction machine, and three-phase load blocks.
- Change the load flow source, synchronous machine, and induction machine blocks' bus type.
- Select and highlight node and connection blocks in the model.
- Sort columns in the tables by increasing or decreasing values.
- Export the data to a spreadsheet, a MAT-file, or a comma-separated variable (CSV) file.

PMSM and BLDC Blocks Enhancements: Model thermal variants with empirical losses

The PMSM and BLDC blocks now support temperature dependency and iron losses. To enable these parameters, right-click the block in your model, select **Simscape > Block choices**, and then select the desired block variant with thermal ports: **Composite three-phase ports | Show thermal port** or **Expanded three-phase ports | Show thermal port**.

SPICE NIGBT block: Model a SPICE-compatible N-Channel insulated gate bipolar transistor

The SPICE NIGBT block models a SPICE n-type insulated gate bipolar transistor (IGBT).

SPICE, or Simulation Program with Integrated Circuit Emphasis, is a simulation tool for electronic circuits. You can convert some SPICE subcircuits into equivalent Simscape Electrical models by using the Environment Parameters block and SPICE-compatible blocks from the “Additional Components” library. For more information, see `subcircuit2ssc`.

Expanded SM Control Library: Speed up modeling by using prebuilt and documented automatic voltage regulators and power system stabilizers blocks

Save time deriving, implementing, testing, debugging, and documenting algorithm models by using blocks from the expanded SM Control library. These Simulink® blocks are modular and decoupled, customizable, and compatible with Embedded Coder®. Each block provides open access to the implementation source code.

To access the new blocks, in the Simulink Library Browser, select **Simscape > Electrical > Control > SM Control** to access:

- Synchronous-machine-type AC blocks — SM AC2C, SM AC3C, SM AC4C, SM AC5C, SM AC6C, SM AC7C, SM AC8C.
- Synchronous-machine-type DC blocks — SM DC1C, SM DC2C.
- Synchronous-machine-type ST blocks — SM ST1C, SM ST2C, SM ST3C, SM ST4C.
- Power system stabilizer (PSS) blocks — SM PSS1A, SM PSS2C, SM PSS7C.

Stepper Motor Block: Select a predefined parameterization

There are now multiple available built-in parameterizations for the Stepper Motor block.

This pre-parameterization data allows you to set up the block to represent a specific supplier component. To load a predefined parameterization, click the “Select a predefined parameterization” hyperlink in the Stepper Motor block mask and select the part you want to upload from the list of available components.

DC Motor Block Enhancement: Generate magnetic fields with new motor field option

You can now specify how to generate the magnetic field of a DC Motor block. Set **Field type** to Permanent magnet to generate the magnetic field using a permanent magnet, or Wound to generate it from the current flowing through the windings.

PMSM (Five-Phase) Block: Model a five-phase permanent synchronous motor

You can use the PMSM (Five-Phase) block to model a five-phase permanent magnet synchronous motor with sinusoidal flux distribution.

To specify the stator configuration, set the **Winding Type** parameter to either Star-wound, Pentacle-wound, or Pentagon-wound.

PMLSM Block: Model a three-phase permanent magnet linear synchronous motor

You can use the PMLSM block to model a three-phase permanent magnet linear synchronous motor with sinusoidal flux distribution.

To specify the stator configuration, set the **Winding Type** parameter to either Wye-wound or Delta-wound.

Electromechanical Library Enhancement: Model some machines with different fidelity levels

To allow for a new level of modeling fidelity, these blocks have been updated:

- BLDC
- Hybrid Excitation PMSM
- PMSM
- Synchronous Reluctance Machine
- Synchronous Machine Model 1.0

To enable the new parameters, set the **Modeling fidelity** parameter to either Constant Ld, Lq, and PM or Tabulated Ld, Lq, and PM.

Inductive Rotor Position Sensor Block: Obtain the rotor position

To obtain the rotor position, the Inductive Rotor Position Sensor block comprises four planar coils and a target trace, and decodes the rotational angle by using the theory of eddy current losses.

Power Transformers Blocks Enhancements: Represent magnetic saturation

The magnetic circuit and equations of these blocks have been redesigned to allow for an accurate representation of a saturable transformer:

- Two-Winding Transformer (Three-Phase)
- Three-Winding Transformer (Three-Phase)
- Zigzag-Delta-Wye Transformer

To represent the magnetic saturation of these blocks, set the **Magnetic saturation representation** parameter to `Lookup table (phi versus i)`.

Distributed Parameter Line Model for Transmission Line Block: Obtain more accurate simulations at a particular frequency

You can now model the Transmission Line block as a distributed parameter line. A distributed parameter line gives more accurate simulations at specified frequencies.

However, this is not a frequency-dependent model and its accuracy will drop outside the frequency point you specify in the **Frequency used for rlcg specification** parameter.

SPICE Diode Block Enhancements: Calculate high-injection knee current, IKF, and recombination current, ISR

The SPICE Diode block now comprises several new parameters: **High-injection knee current, IKF** and **Recombination current, ISR**.

N-Channel MOSFET and P-Channel MOSFET Block Enhancements: Parameterize four terminals

In order to access bulk, the N-Channel MOSFET and P-Channel MOSFET blocks now support four electrical nodes parameterization.

To enable the new port and parameters, in the block dialog box, in the **Main** settings, set **Parameterization** to `Four terminals`.

SPMT Switch Block: Model a single-pole multiple-throw switch

The SPMT Switch block models a single-pole multiple-throw switch. You can specify three to eight throw connections by setting the **Number of throw ports** to the desired amount.

Open connections are modeled by a resistor with a value equal to the reciprocal of the **Open conductance** parameter value. Closed connections are modeled by a resistor with a value equal to the **Closed resistance** parameter value.

Average-Value Chopper and Average-Value DC-DC Converter Blocks Enhancement: Model conduction loss dependencies by using tabulated efficiency parameterization

To model conduction loss dependencies on the provided output current, the Average-Value Chopper and Average-Value DC-DC Converter blocks now support tabulated efficiency parameterization.

Set the **Converter efficiency** parameter to **Tabulated** and specify the desired values for the **Output current vector** and **Efficiency vector (%)** parameters.

Average-Value DC-DC Converter Block Enhancement: Use voltage and current reference as control inputs

To convert the electrical energy between the connected components on either side of the converter, the Average-Value DC-DC Converter block now supports voltage and current references as control inputs.

If you set the **Control input** parameter to **Current** reference, the converter sets the output current and it computes the voltage.

Similarly, if you set the **Control input** parameter to **Voltage** reference, the converter sets the output voltage and it computes the current.

DC-DC Converter Block Enhancement: Model the voltage reference externally

You can now model the voltage reference inside the DC-DC Converter block as an external input.

To expose the voltage reference port, set the **Voltage reference** parameter to **External**.

Battery (Table-Based) Block Enhancement: Select additional extrapolation and interpolation options for table-based parameters

The Battery (Table-Based) block can now use nearest interpolation and extrapolation methods for all table-based parameters, or no extrapolation at all.

You can set the **Extrapolation method for all tables** parameter to:

- **Linear** — Estimates values beyond the dataset by creating a tangent line at the end of the known data and extending it beyond that limit.
- **Nearest** — Extrapolates a value at query point that is the value at the nearest sample grid point.
- **Error** — Returns an error if the value goes beyond the known dataset. If you select this option, the block does not use extrapolation.

Turbine-Governors Blocks: Implement speed-governing steam or hydropower turbine models and load controllers

A new Turbine-Governors category has been added to the Control library. You can use the blocks from this library to implement speed-governing steam or hydropower turbine models and load controllers:

- Controller LCFB1
- Governor Type 1
- Governor Type 3

Phasor Measurement Unit (PMU, Three-Phase) Block: Measure the positive sequence component of the frequency, phase, and amplitude of the input signal

The Phasor Measurement Unit (PMU, Three-Phase) block measures the frequency, phase, and amplitude of the positive sequence component of the input electrical signal in a three-phase system.

Programmable Signal Generator block: Generate a three-phase sinusoidal signal with programmable magnitude, phase, and frequency over time

The Programmable Signal Generator (Three-Phase) block generates a three-phase sinusoidal signal with programmable magnitude, phase, and frequency over time. You can specify one or two harmonics that can be overlapped on the signal fundamental frequency.

Moving Average (Variable Frequency) Block: Output the moving average value of an input signal of variable frequency

To filter higher-frequency signal components and smooth noisy signals, the Moving Average (Variable Frequency) block computes the moving average value of an input signal of variable frequency.

Sine Wave Generator (Three-Phase) Block: Generate a balanced three-phase sine wave

The Sine Wave Generator (Three-Phase) block uses the magnitude, phase shift, and frequency inputs to generate a balanced three-phase sine wave.

Stair Generator Block: Generate a stair pattern signal based on specified values

The Stair Generator block generates a custom stair signal based on the values specified in the **Time (s)** and **Amplitude** parameters.

Constant Power Load Block: Model a faultable constant power load for a DC supply

The Constant Power Load block implements a constant power load for a DC supply. The load behavior changes according to the voltage received from the DC supply.

You can model an electrical fault as an open circuit by setting the **Enable open circuit fault** parameter to Yes.

General Control Blocks Enhancement: Specify initialization options

You can now specify the initial conditions for these blocks:

- Filtered Derivative (Discrete or Continuous)
- Lead-Lag (Discrete or Continuous)
- Low-Pass Filter (Discrete or Continuous)
- Second-Order Low-Pass Filter (Discrete or Continuous)
- Washout (Discrete or Continuous)

To enable the **Initial state** parameter, set **Initialization** to Specify as parameter.

SPICE Conversion Assistant: Use derivative SPICE function

The SPICE Conversion Assistant now supports the derivative SPICE function, `ddt`. For more information, see “Converting a SPICE Netlist to Simscape Blocks”.

SPICE Current Sources Blocks: Specify behavior of parallel conductance

You can now fully specify the behavior of the parallel conductance, *GMIN*, for these blocks:

- DC Current Source
- Exponential Current Source
- PCCCS
- PCCCS2
- Piecewise Linear Current Source
- Pulse Current Source
- PVCCS
- PVCCS2
- SFFM Current Source
- Sinusoidal Current Source

The value of the parallel conductance, *GMIN*, depends on whether your model contains an Environment Parameters block.

This table shows the possible values of *GMIN*:

Values of parallel conductance, GMIN

Include parallel conductance, GMIN	
Yes	No
Model contains Environment Parameters block	Model does not contain Environment Parameters block
<i>GMIN</i> is equal to the value of the GMIN parameter in the Environment Parameters block.	<i>GMIN</i> = 1e-12 Ohm
	Parallel conductance, <i>GMIN</i> , is not included and it does not affect the current source.

P-Channel MOSFET Block: Changes on order and location of s and d ports

The ports order and location of the surface-potential-based variant of the P-Channel MOSFET block are now consistent with those of its threshold-based variant.

Featured Examples

New examples in this release include:

- “Solar PV System with MPPT Using Boost Converter” — Design a boost converter to control the power output of a solar PV system by using maximum power point tracking technique .
- “Stand-Alone Solar PV AC Power System with Battery Backup” — Design a standalone PV AC power system with battery backup.
- “Stand-Alone Solar PV DC Power System with Battery Backup” — Design a standalone PV DC power system with battery backup.
- “Single-Phase Grid-Connected Solar Photovoltaic System”
- “Three-Phase Grid-Connected Solar Photovoltaic System”
- “SPICE Conversion of a CMOS Voltage Comparator” — Convert a SPICE implementation of a CMOS voltage comparator to a Simscape component and compare the results.
- “Troubleshoot a SPICE Conversion of an IGBT Subcircuit” — Troubleshoot the conversion of a SPICE insulated gate bipolar transistor (IGBT) subcircuit and convert it into an equivalent Simscape component.
- “Five-Phase PMSM Velocity Control” — Control the rotor angular velocity in an electrical-traction drive based on a five-phase permanent magnet synchronous machine (PMSM).
- “Five-Phase PMSM Torque Control” — Control the torque in an electrical-traction drive based on a five-phase permanent magnet synchronous machine (PMSM).
- “Three-Phase PMLSM Drive” — Control the position in a three-phase permanent magnet linear synchronous machine (PMLSM) drive.
- “DC-DC Converter Model Fidelity Comparison” — Compare simulation results using different levels of fidelity in DC-DC converters.
- “Chopper Model Fidelity Comparison” — Compare simulation results using different levels of fidelity in chopper converters.

- “Calculate Performance Curves of BLDC” — Calculate the peak torque, power, current, and efficiency values of a brushless DC (BLDC) motor for a given speed.
- “Single-Phase PMSM Control” — Control the rotor speed of an electrical drive based on a single-phase permanent magnet synchronous machine (PMSM).

Specialized Power Systems

Powergui Block: Use the discrete phasor solver type to discretize and solve electrical networks in phasor mode

The discrete phasor solver type uses simplified machine models where differential equations on the stator side are replaced with algebraic equations. These lower-order machine models produce simulation results similar to commercial stability software. The solver uses a robust solution method that allows you to eliminate machine parasitic loads and use Simulink Coder to generate code and simulate your model in real time.

PV Array Block: Use the robust discrete model to discretize PV Array blocks

The robust solver iterates to resolve the algebraic loop in internal diode models at a specified cell temperature. The robust solver is the recommended method for discretizing the PV Array blocks.

Power_flicker Function: Analyze the short-term and long-term flicker severity of an instantaneous flicker level signal shorter than 10 minutes

The new function allows you to specify a short-term observation interval that is shorter than the 10 minutes (600 seconds) default setting defined by the IEC standard. The short-term flicker severity and long-term flicker severity are computed for the specified observation interval period.

Featured Examples

New examples in this release include:

- “2-MW PV Farm Connected to a 25-kV Distribution System” — Show how to connect PV Arrays to a distribution system using DC boost converters driven by Maximum Power Point Tracker (MPPT) controllers.
- “PV Home On-Grid Solar System” — Show the operation of a photovoltaic residential system connected to the electrical grid.

R2019b

Version: 7.2

New Features

Bug Fixes

Compatibility Considerations

Simscape Electrical

Load-Flow Analysis: Determine nodal voltages and real and reactive power flows in Simscape Electrical networks

You can now perform a load-flow analysis on models built using Simscape components by using new load-flow blocks and updated machine blocks. You can use the load-flow results to initialize dynamic AC simulation.

The new load-flow blocks are:

- Load Flow Source block — Model a swing, PV, or PQ bus, or a voltage with source impedance.
- Busbar block — Model a load-flow bus with up to four connections.

These machine blocks now have load-flow compatible AC steady-state initialization options:

- Induction Machine Squirrel Cage
- Induction Machine Wound Rotor
- Synchronous Machine Model 2.1
- Synchronous Machine Salient Pole
- Synchronous Machine Round Rotor

For examples that show how to perform a load-flow analysis for a Simscape electrical network, see:

- 2-Bus Load Flow
- IEEE 9-Bus Load Flow
- Induction Motor Initialization with Load Flow
- Synchronous Machine Initialization with Load Flow

Isothermal and Fade Models for Battery Blocks: Specify fade data using temperature-dependent or temperature-independent parameterization

The Battery and Battery (Table-Based) blocks now support advanced battery fade modeling through both temperature-independent and temperature-dependent tabulated parameterization. The blocks can also calculate the no-load voltage as a function of temperature.

Thermal Model Improvements for Semiconductors: Model external thermal dynamics using Cauer and Foster representations

You can now model a fully external thermal network by removing the internal thermal network of certain semiconductor blocks. You can also model thermal dynamics using both Cauer and Foster thermal representations.

Expanded Support for Power Dissipation Data: View power_dissipated simulation logging data for all machine blocks

You can now analyze data for a power_dissipated logging node for all induction, permanent magnet, reluctance, and synchronous machines in the Electromechanical library. For more information on logging, viewing, and analyzing power_dissipated data, see:

- About the Simscape Results Explorer (Simscape)
- Data Logging (Simscape)
- sscexplore
- ee_getEfficiency
- ee_getPowerLossSummary
- ee_getPowerLossTimeSeries

Average-Value PWM for Three-Phase Converter Block: Use averaged firing pulses for PWM-controlled power conversion

The Converter (Three-Phase) block now allows you to model an ideal three-phase converter that is controlled by either averaged PWM signals or modulation waveforms. To model an ideal three-phase converter that can accept averaged gate signals, in the **Switching Devices** settings for the block, set the **switching device** parameter to Averaged switch.

Japanese Language Localization Support: Block parameters, variables, and error messages are available in Japanese

Simscape Electrical is available in Japanese for Japanese-localized systems. For more information, see Internationalization.

Expanded Control Library: Speed up modeling by using prebuilt and documented algorithm components

Save time deriving, implementing, testing, debugging, and documenting algorithm models by using blocks from the expanded Control library. The blocks are Simulink blocks that are modular and decoupled, customizable, and compatible with Embedded Coder. Each block provides open access to the implementation source code.

To access the new blocks, in the Simulink Library Browser, select **Simscape > Electrical > Control**, and then:

- **Measurements** — To access the Total Harmonic Distortion block.
- **Observers** — To access the Resolver-to-Digital Converter and Quadrature Shaft Decoder blocks.
- **Pulse Width Modulation** — To access the PWM Generator (Vienna Rectifier) block.

Hall-Effect Rotary Encoder Block: Convert Hall-effects into voltage and phase angle or angular position

To model a 360° rotary position sensor, the Hall-Effect Rotary Encoder block uses four equally spaced Hall elements and a rotating magnet to generate four sinusoidal waveforms.

Passive Harmonic Filter (Three-Phase) Block: Improve power quality

To suppress system harmonic currents and decrease voltage distortion, the Passive Harmonic Filter (Three-Phase) block provides low-impedance paths for specified harmonics. At rated frequency, the passive shunt filters are capacitive. The capacitive filters provide reactive power that improves power factor.

Sequence Analyzer Block: Calculate magnitude and phase of the sequence of a three-phase signal

The Sequence Analyzer block outputs the magnitude and phase of the positive-sequence, negative-sequence, or zero-sequence components of a three-phase input signal.

Single-Phase and Three-Phase Fault Block Improvements: Limit fault duration time and specify both event-based and temporal faults for both fault blocks

The Fault block, a single-phase block, now allows you to limit the duration time for a temporal fault. To limit the fault duration, in the **Temporal Trigger** settings, change the value of the **Fault duration** parameter from `inf` to a nonnegative number.

The Fault (Three-Phase) block, replaces both the Enabled Fault and the Time-Based Fault. The merged block allows you to:

- Set externally triggered faults using either a specified threshold value or a physical input signal.
- Set temporally triggered faults.
- Reenter the unfaulted state for both externally and temporally triggered faults.
- View the fault state.

Compatibility Considerations

For information on issues related to block name changes, see “Compatibility Considerations” on page 2-9.

SPST and SPDT Relay Blocks: Model a controlled single-pole single-throw or double-throw relay with faults and delays

The SPST Relay and SPDT Relay blocks allow you to:

- Control the relay state using a physical signal input port or electrical conserving ports
- Output the relay state
- Delay the breaking and making of connections
- Introduce a behavioral or temporal fault that results in a stuck connection, an open circuit, or degraded contact resistance

The SPDT Relay block replaces the Relay.

Compatibility Considerations

For information on issues related to block name changes, see “Compatibility Considerations” on page 2-9.

Nonlinear Reluctance with Saturation: Include different levels of linearity and saturation in magnetic reluctance

The Nonlinear Reluctance block replaces the Reluctance with Hysteresis block. The Nonlinear Reluctance block provides these parameterization models:

- Linear reluctance.
- Reluctance with single saturation point.
- Reluctance (B-H curve).
- Nonlinear reluctance with hysteresis. For this implementation, the block uses the Jiles-Atherton model, as was provided by the Reluctance with Hysteresis block, with the new nonlinearity capability.

Compatibility Considerations

For information on issues related to block name changes, see “Compatibility Considerations” on page 2-9.

Three-Winding Nonlinear Transformer: Model varying levels of nonlinearity for a transformer with two secondary windings

The Three-Winding Nonlinear Transformer block allows you to model varying levels of nonlinearity, set initial current or flux for each winding, and include parasitic conductance. The Three-Winding Nonlinear Transformer block allows you to simulate circuit topologies that you cannot model using multiple Nonlinear Transformer blocks.

Zigzag-Delta-Wye Transformer block: Model a linear, nonideal zigzag-delta-wye transformer with a zigzag interconnect port

The Zigzag-Delta-Wye Transformer block replaces the Zigzag-Delta1-Wye Transformer and Zigzag-Delta11-Wye Transformer blocks. The new block provides these configuration options for the delta winding:

- Delta 1 o'clock
- Delta 11 o'clock

To access the winding interconnect port, in the **Main** settings, set the **Zigzag configuration** parameter to **Accessible winding interconnects**.

Compatibility Considerations

For information on issues related to block name changes, see “Compatibility Considerations” on page 2-9.

Delta-Wound PMSM and BLDC Motor Models: Increase motor speed range by applying the full voltage across all three phases

The BLDC, PMSM, and FEM-Parameterized PMSM blocks now support a delta-wound configuration. Due to the full utilization of terminal voltage, delta windings allow you to increase the constant power speed range and provide higher efficiency than wye windings.

To model a delta winding, in the block settings, set the **Winding type** parameter to Delta-wound.

Dielectric Relaxation Model for Capacitor Block: Model both resistive and dielectric losses

To represent both resistive and dielectric capacitance losses, the Capacitor block uses the Debye dielectric relaxation model. The Debye model considers a collection of noninteracting dipoles in the frequency domain. To use this frequency-dependent, lossy capacitor model, in the **Main** settings of the Capacitor block, set the **Capacitance** parameter to Dielectric relaxation (Debye).

H-Bridge Block Voltage Supply Ports: Model external DC power for a PWM-controlled H-bridge motor drive

You can now model DC voltage demand by exposing the internal supply rail connections of an H-Bridge block that simulates in PWM mode. To expose the power supply ports on an H-Bridge block, in the **Simulation Mode & Load Assumptions** settings, set the **Power supply** parameter to External.

The H-Bridge block also has a new parameter that determines the circumstances for applying the regenerative braking model when the **Simulation mode** parameter for the block is set to Averaged. You can now apply regenerative braking regardless of the voltage applied at the **REV** port for controlling block output polarity reversal, the H-Bridge. Alternatively, you can make the application of regenerative braking dependent on the state of the **REV** port and the direction of current.

Harmonic Generation Time Limits for Voltage Source Blocks: Set start and stop times for generating source harmonics in the single and three-phase programmable voltage source blocks

For both the Programmable Voltage Source and Programmable Voltage Source (Three-Phase) blocks, you can now start generating source harmonics after the start of simulation and stop generating the harmonics before the end of simulation. To set time limits for generating source harmonics, in the block **Harmonics** settings, set **Source harmonics** to Generate harmonics, and then, specify simulation times for one or both of these parameters:

- **Start time**
- **Stop time**

Solenoid Block Orientation: Set the direction of force between the solenoid plunger and case

You can now specify the direction of action for the Solenoid block. Depending on the setting that you choose for the **Motion direction under excitation** parameter, a positive current from the electrical

+ port to the electrical - port can yield either a pulling or a pushing force from the mechanical **C** port to the mechanical **R** port.

When you change the direction of the force between the mechanical ports, the relative positions of the case and plunger on the icon of the Solenoid block change accordingly.

Voltage Plots for CMOS Logic Blocks: Visualize voltage data for integrated circuit models

These complementary metal-oxide-semiconductor (CMOS) logic blocks now create plots of the voltage at each electrical port:

- CMOS AND
- CMOS NAND
- CMOS OR
- CMOS NOT
- CMOS NOR
- CMOS XOR

To create voltage plots for a CMOS block, right-click the block and, from the context menu, select **Electrical > Basic Characteristics**.

Run-Time Tolerance Parameters: Modify fractional and random tolerance parameters for capacitance, inductance, and resistance without recompiling

You can now designate fractional and random tolerance parameters for these blocks as run-time tunable:

- Capacitor
- Diffusion Resistor
- Inductor
- Mutual Inductor
- Resistor

If you designate a parameter as run-time tunable and use a variable to define the parameter value, you can apply a value change between simulation runs without recompiling. For more information about run-time parameters for Simscape blocks, see Run-Time Parameters.

Block Name Changes and Mergers: Easily identify and configure modeling components

Block names were updated to better indicate the functionality and the electrical domain of the component. Merged blocks combine several model variants in a single block.

Additional functionality is available, as indicated, for some of the renamed and merged blocks.

Block Name Changes and Mergers

R2019a Block Name	R2019b Block Name	Merger	Additional Functionality
Enabled Fault	Fault (Three Phase)	Time-Based Fault	See “Single-Phase and Three-Phase Fault Block Improvements: Limit fault duration time and specify both event-based and temporal faults for both fault blocks” on page 2-4
Relay	SPDT Relay	Not applicable	See “SPST and SPDT Relay Blocks: Model a controlled single-pole single-throw or double-throw relay with faults and delays” on page 2-4
Reluctance with Hysteresis	Nonlinear Reluctance	Not applicable	See “Nonlinear Reluctance with Saturation: Include different levels of linearity and saturation in magnetic reluctance” on page 2-5
Time-Based Fault	Fault (Three Phase)	Enabled Fault	See “Single-Phase and Three-Phase Fault Block Improvements: Limit fault duration time and specify both event-based and temporal faults for both fault blocks” on page 2-4
Zigzag-Delta1-Wye Transformer	Zigzag-Delta-Wye Transformer	Zigzag-Delta11-Wye Transformer	See “Zigzag-Delta-Wye Transformer block: Model a linear, nonideal zigzag-delta-wye transformer with a zigzag interconnect port” on page 2-5
Zigzag-Delta11-Wye Transformer	Zigzag-Delta-Wye Transformer	Zigzag-Delta1-Wye Transformer	See “Zigzag-Delta-Wye Transformer block: Model a linear, nonideal zigzag-delta-wye transformer with a zigzag interconnect port” on page 2-5

Compatibility Considerations

If you reference a block within a library by an obsolete block name in MATLAB® code, the code generates an error.

For example, the Relay block has been renamed the SPDT Relay block and moved from the **Simscape > Electrical > Switches & Breakers** library to the **Simscape > Electrical > Switches & Breakers > Relays** library.

Suppose an existing model named **modelName** contains an SPDT Relay block. When you open the model using the R2019a version of Simscape Electrical, the block is still named **Relay**. A function that calls the block in the model as an argument does not generate an error if it uses this syntax:

```
functionName('modelName/Relay','argument2',...,'argumentX')
```

However, the code generates an error if it uses a function to add an SPDT Relay from the Switches & Breakers library, or in any other way changes the SPDT Relay block that is in the library by using this syntax:

```
functionName('ee_lib/Switches & Breakers/Relay','argument2',...,'argumentX')
```

To prevent this type of error, use this syntax in your code:

```
functionName('ee_lib/Switches & Breakers/Relays/SPDT Relay','argument2',...,'argumentX')
```

If your code generates an error, it could contain an obsolete name as an argument in a function for adding or changing a block that is in a library. Some functions that are commonly used to manipulate blocks and block properties are:

- add_block
- set_param
- get_param

Featured Examples

New examples in this release include:

- 2-Bus Loadflow — Model a three-phase power system network that includes a swing bus and a PV bus.
- IEEE 9-Bus Loadflow — Model a 9-bus three-phase power system network based on an IEEE benchmark test case.
- Induction Motor Initialization with Loadflow — Initialize a three-phase induction motor using data from a load-flow analysis.
- Synchronous Machine Initialization with Loadflow — Initialize a synchronous machine using data from a load-flow analysis.
- Battery Parameter Extraction from Data — Specify Battery block parameters to fit data defined over different temperatures.
- Power Converter Model Fidelity Comparison — Model a three-phase matrix converter that drives a static load and draws unity power factor at the source.
- Three-Phase Matrix Converter — Model a three-phase matrix converter that drives a static load and draws unity power factor at the source.
- Photovoltaic Thermal (PV/T) Hybrid Solar Panel — Model a cogeneration system that contains electrical, thermal, and thermal-liquid components.

- Stepper Motor Pull-In Characteristics — Validate a model using manufacturer datasheets and pre-parameterized models.
- Clocked Reset-Dominant SR-Latch — Model a reset-dominant SR-Latch by using logic components.
- Clocked Set-Dominant SR-Latch — Model a set-dominant SR-Latch by using logic components.
- Earthing Effects with Unbalanced Load — See how various reference blocks affect the voltage and current of a connected network.

Specialized Power Systems

Expanded Automatic Advanced Settings Handling: Simplify discrete simulation settings for machine models by using the powergui block discrete solver

For some machine models, the powergui block discrete solver determines values that you would otherwise have to specify in the advanced simulation settings of the connected block. The simplified simulation settings can now be used with the Simplified Synchronous Machine block, the Permanent Magnet Synchronous Machine blocks, and the double squirrel-cage rotor-type model for the per-unit and SI Asynchronous Machine blocks.

To use automatic handling for advanced settings of machine blocks:

- 1 Open the settings for the attached powergui block.
- 2 In the **Solver** settings, for the **Simulation** parameter, select **Discrete**.
- 3 In **Preferences**, select the **Automatically handle the Discrete solver and Advanced tab solver settings of blocks** option.

Discrete Load and Transformer Blocks: Build models for discrete-time simulation using nonlinear and variable blocks

You can use the discrete solver capability of the powergui block to calculate results from models that contain one of these new blocks from the Elements library:

- Nonlinear Inductor
- Nonlinear Resistor
- Variable Capacitor
- Variable Inductor
- Variable-Ratio Transformer
- Variable Resistor

Pulse-Averaging and Interpolating PWM Blocks: Use advanced pulse generation techniques for high-precision motor control

The PWM Generator (Interpolation) and PWM Generator (Pulse Averaging) blocks control electronic converters using carrier-based unipolar pulse width modulation. Both blocks generate pulses for these converter types:

- Two-quadrant
- Full-bridge, single-phase
- Two-level, three-phase
- Three-level, three-phase

Featured Example

The On Load Tap Changer (OLTC) Regulating Transformer Using Variable-Ratio Transformer Blocks example shows how to regulate a positive-sequence voltage at a transmission network 25 kV bus by using an on-line tap changer (OLTC) transformer.

R2019a

Version: 7.1

New Features

Bug Fixes

Compatibility Considerations

Simscape Electrical

Dynamic Load (Three-Phase) Block: Model a four-quadrant dynamic load

The Dynamic Load (Three-Phase) block models a four-quadrant load that you can vary over the course of simulation. You specify the real and reactive power demand of the block using a physical signal input port.

Controlled Voltage Source (Three-Phase) Block: Apply an ideal controlled three-phase voltage to your network

The Controlled Voltage Source (Three-Phase) block maintains the specified voltage regardless of the load. You specify the reference voltage using a physical signal input port.

Current and Voltage Sensor (Three-Phase) Block: Measure current and voltage at three-phase electrical nodes

The Current and Voltage Sensor (Three-Phase) block represents an ideal three-phase voltage and current sensor. It measures voltage and current of a three-phase electrical node and outputs two three-element physical signal vectors.

PS Output Port for Fuse and Relay Blocks: Output block state as physical signal

Optional PS output ports on Fuse and Relay blocks let you output the block state as a physical signal. The port visibility is controlled by a new parameter in the block dialog box:

- Fuse block — The parameter name is **PS output for fuse state**. The default value is `Hidden`. When you set it to `Visible`, a PS output port **x** appears on the block icon. The port outputs 0 if the fuse is intact, and 1 if the fuse is blown.
- Relay block — The parameter name is **PS output for relay state**. The default value is `Hidden`. When you set it to `Visible`, a PS output port **x** appears on the block icon. The port outputs a vector of length two, the first element corresponding to the C-S1 connection and the second to the C-S2 connection. The elements are 1 if the corresponding connection is closed, and 0 otherwise.

Pressure Transducer Block Measurement Port: Select domain type for pressure measurement

The Pressure Transducer block turns a pressure measurement into voltage. The block now lets you measure pressure in a variety of domains. The new **Fluid port type** parameter has these options:

- Hydraulic
- Thermal Liquid
- Gas (default)
- Moist Air

- Two-Phase Fluid

Compatibility Considerations

In previous releases, the Pressure Transducer block had a pneumatic measurement port. Pneumatic blocks are no longer part of the Foundation library, but they are included in the Simscape product installation as an example custom library. The legacy Pressure Transducer block, with a pneumatic port, is now part of this custom library. From 2019a, use the Gas library for modeling pneumatic systems, and use the latest version of the Pressure Transducer block with a gas port. For more information, see Gas Domain and Block Library: Model gas systems with various levels of idealization (Simscape).

Earthing Transformer Block: Create a neutral point for your three-phase power network

The Earthing Transformer block is a three-phase coupler that provides your power system with a **neutral** connection for earthing.

Frequency-Dependent Overhead Line (Three-Phase) Block: Model a three-phase line over a wide range of frequencies

The Frequency-Dependent Overhead Line (Three-Phase) block generates frequency-dependent parameters that consider skin effect and earth return based on the simplified parameters that you specify. The block is suitable for power-system transient and harmonic analyses.

Programmable Voltage Source Blocks: Provide a single-phase or three-phase voltage with programmable magnitude, frequency, and phase shift to your network

The Programmable Voltage Source block models a single-phase AC voltage source with programmable magnitude, frequency, phase shift, and DC voltage offset. You can also include harmonics and noise in the voltage source.

The Programmable Voltage Source (Three-Phase) block models a three-phase voltage source with programmable AC magnitude, frequency, and phase shift. You can also include impedance and harmonics in the voltage source.

For both blocks, you can parameterize each programmable property individually using:

- A constant value
- A ramp
- A step
- Modulation

Alternatively, you can input a property using an external signal connected to a physical signal input port on the single-phase or three-phase programmable voltage source block.

Restructured Libraries: Easily discover blocks for building networks that have the right mix of performance and fidelity for your model-based design goals

Electronics and Mechatronics and **Power Systems**, two of the three top-level Simscape Electrical block libraries have been integrated. Some library names are changed to reflect the commonality of blocks that they now contain.

To open the top-level block library, at the MATLAB command prompt, enter `simscapeelectrical` or `ee_lib`.

Library Restructure

R2018b	R2019a
Electronics and Mechatronics <ul style="list-style-type: none"> • Actuators and Drivers • Integrated Circuits • Logic • Passive Devices • Switches • Semiconductor Devices • Sensors • Sources 	Connectors and References Control Electromechanical Integrated Circuits Semiconductors and Converters Passive Sensors and Transducers Sources
Power Systems <ul style="list-style-type: none"> • Connections • Control • Machines • Passive Devices • Semiconductors • Sensors • Sources • Switches and Breakers 	Switches and Breakers Utilities Additional Components
Specialized Power Systems	Specialized Power Systems

Compatibility Considerations

MATLAB code generates an error if a function argument includes:

- The previous name of a library
- The incorrect 'libraryName/block Name' combination

Block Name Changes and Mergers: Updated block names and merged blocks allow you to easily identify and configure model components

Block names have been updated to better indicate the functionality and the electrical domain, in terms of the number of phases, of the component.

Merged machine blocks allow you to easily switch between SI and per-unit parameterizations. Merged diode, transformer, switch, and reluctance machine blocks combine several model variants in a single block.

Block Name Changes and Mergers

Block Name Prior to R2019a	Block Name from R2019a	Merger
AC Cable	AC Cable (Three-Phase)	N/A
ASM Current Controller	Induction Machine Current Controller	N/A
ASM Direct Torque Control	Induction Machine Direct Torque Control	N/A
ASM Direct Torque Control with Space Vector Modulator	Induction Machine Direct Torque Control with Space Vector Modulator	N/A
ASM Field-Oriented Control	Induction Machine Field-Oriented Control	N/A
ASM Flux Observer	Induction Machine Flux Observer	N/A
ASM Scalar Control	Induction Machine Scalar Control	N/A
Asynchronous Machine Measurement	Induction Machine Measurement	N/A
Asynchronous Machine Squirrel Cage (fundamental)	Induction Machine Squirrel Cage	Asynchronous Machine Squirrel Cage (fundamental, SI)
Asynchronous Machine Squirrel Cage (fundamental, SI)	Induction Machine Squirrel Cage	Asynchronous Machine Squirrel Cage (fundamental)
Asynchronous Machine Wound Rotor (fundamental)	Induction Machine Wound Rotor	Asynchronous Machine Wound Rotor (fundamental, SI)
Asynchronous Machine Wound Rotor (fundamental, SI)	Induction Machine Wound Rotor	Asynchronous Machine Wound Rotor (fundamental)
Average-Value Inverter	Average-Value Inverter (Three-Phase)	N/A
Average-Value Rectifier	Average-Value Rectifier (Three-Phase)	N/A
Average-Value Voltage Source Converter	Average-Value Voltage Source Converter (Three-Phase)	N/A
Brushless DC Motor	BLDC	N/A
Commutation Diode	Diode	Diode Diode (Piecewise Linear)
Converter	Converter (Three-Phase)	N/A
Coupled Lines	Coupled Lines (Three-Phase)	N/A
Current Sensor	Current Sensor (Three-Phase)	N/A
Delta Reference	Delta Reference (Three-Phase)	N/A

Block Name Prior to R2019a	Block Name from R2019a	Merger
Delta11-Delta11-Wye Transformer	Three-Winding Transformer (Three-Phase)	Delta1-Delta1-Wye Transformer Wye-Delta11-Wye Transformer Wye-Delta1-Wye Transformer
Delta1-Delta1-Wye Transformer	Three-Winding Transformer (Three-Phase)	Delta11-Delta11-Wye Transformer Wye-Delta11-Wye Transformer Wye-Delta1-Wye Transformer
Delta-Delta Transformer	Two-Winding Transformer (Three-Phase)	Wye-Delta1 Transformer Wye-Delta11 Transformer Wye-Wye Transformer
Diode	Diode	Commutation Diode Diode (Piecewise Linear)
Five-Phase Switched Reluctance Machine	Switched Reluctance Machine (Multi-Phase)	Four-Phase Switched Reluctance Machine
Four-Phase Switched Reluctance Machine	Switched Reluctance Machine (Multi-Phase)	Five-Phase Switched Reluctance Machine
Diode (Piecewise Linear)	Diode	Commutation Diode Diode
Floating Neutral	Floating Neutral (Three-Phase)	N/A
Grounded Neutral	Grounded Neutral (Three-Phase)	N/A
Hybrid Excitation Synchronous Machine	Hybrid Excitation PMSM	N/A
IGBT	IGBT (Ideal, Switching)	N/A
Induction Motor	Simplified Induction Motor	N/A
Line Voltage Sensor	Line Voltage Sensor (Three-Phase)	N/A
Machine Mechanical Power (pu)	Machine Mechanical Power	Machine Mechanical Power (SI)
Machine Mechanical Power (SI)	Machine Mechanical Power	Machine Mechanical Power (pu)
MOSFET	MOSFET (Ideal, Switching)	N/A
Neutral Port	Neutral Port (Three-Phase)	N/A
Open Circuit	Open Circuit (Three-Phase)	N/A
Permanent Magnet Synchronous Motor	PMSM	N/A
Phase Voltage Sensor	Phase Voltage Sensor (Three-Phase)	N/A

Block Name Prior to R2019a	Block Name from R2019a	Merger
Piezo Linear Motor	Piezo Linear Actuator	N/A
Piezo Rotary Motor	Piezo Rotary Actuator	N/A
PWL Current Source	Piecewise Linear Current Source	N/A
PWL Voltage Source	Piecewise Linear Voltage Source	N/A
Rectifier	Rectifier (Three-Phase)	N/A
RLC	RLC (Three-Phase)	N/A
Servomotor	Simplified PMSM Drive	N/A
Single-Phase ASM Direct Torque Control	Induction Machine Direct Torque Control (Single-Phase)	N/A
Single-Phase ASM Field-Oriented Control	Induction Machine Field-Oriented Control (Single-Phase)	N/A
Single-Phase Asynchronous Machine (fundamental)	Induction Machine (Single-Phase)	Single-Phase Asynchronous Machine (fundamental, SI)
Single-Phase Asynchronous Machine (fundamental, SI)	Induction Machine (Single-Phase)	Single-Phase Asynchronous Machine (fundamental)
Single-Phase Circuit Breaker	Circuit Breaker	N/A
Single-Phase Circuit Breaker (with arc)	Circuit Breaker (with arc)	N/A
Single-Phase Permanent Magnet Synchronous Motor	PMSM (Single-Phase)	N/A
Single-Phase Switch	SPST Switch	SPST Switch
Single-Phase Two-Way Switch	SPDT Switch	SPDT Switch
SPDT Switch	SPDT Switch	Single-Phase Two-Way Switch
SPICE Environment Parameters	Environment Parameters	N/A
SPST Switch	SPST Switch	Single-Phase Switch
Switch	SPST Switch (Three-Phase)	N/A
Switched Reluctance Machine	Switched Reluctance Machine	Switched Reluctance Motor
Switched Reluctance Motor	Switched Reluctance Machine	Switched Reluctance Machine
Synchronous Machine Field Circuit (pu)	Synchronous Machine Field Circuit	Synchronous Machine Field Circuit (SI)
Synchronous Machine Field Circuit (SI)	Synchronous Machine Field Circuit	Synchronous Machine Field Circuit (pu)
Synchronous Machine Model 1.0 (SI parameters)	Synchronous Machine Model 1.0	N/A
Synchronous Machine Model 2.1 (fundamental)	Synchronous Machine Model 2.1	Synchronous Machine Model 2.1 (standard)
Synchronous Machine Model 2.1 (standard)	Synchronous Machine Model 2.1	Synchronous Machine Model 2.1 (fundamental)

Block Name Prior to R2019a	Block Name from R2019a	Merger
Synchronous Machine Round Rotor (fundamental)	Synchronous Machine Round Rotor	Synchronous Machine Round Rotor (standard)
Synchronous Machine Round Rotor (standard)	Synchronous Machine Round Rotor	Synchronous Machine Round Rotor (fundamental)
Synchronous Machine Salient Pole (fundamental)	Synchronous Machine Salient Pole	Synchronous Machine Salient Pole (standard)
Synchronous Machine Salient Pole (standard)	Synchronous Machine Salient Pole	Synchronous Machine Salient Pole (fundamental)
Three-Level Converter	Three-Level Converter (Three-Phase)	N/A
Three-Phase Bridge Cycloconverter Voltage Controller	Bridge Cycloconverter Voltage Controller (Three-Phase)	N/A
Three-Phase Hysteresis Current Controller	Hysteresis Current Controller (Three-Phase)	N/A
Three-Phase Power Measurement	Power Measurement (Three-Phase)	N/A
Three-Phase Sinusoidal Measurement (PLL)	Sinusoidal Measurement (PLL, Three-Phase)	N/A
Thyristor Rectifier Voltage Controller	Thyristor Rectifier Voltage Controller (Three-Phase)	N/A
Two-Way Switch	SPDT Switch (Three-Phase)	N/A
Wye-Delta1 Transformer	Two-Winding Transformer (Three-Phase)	Delta-Delta Transformer Wye-Delta11 Transformer Wye-Wye Transformer
Wye-Delta11 Transformer	Two-Winding Transformer (Three-Phase)	Delta-Delta Transformer Wye-Delta1 Transformer Wye-Wye Transformer
Wye-Delta11-Wye Transformer	Three-Winding Transformer (Three-Phase)	Delta11-Delta11-Wye Transformer Delta1-Delta1-Wye Transformer Wye-Delta1-Wye Transformer
Wye-Delta1-Wye Transformer	Three-Winding Transformer (Three-Phase)	Delta11-Delta11-Wye Transformer Delta1-Delta1-Wye Transformer Wye-Delta11-Wye Transformer

Block Name Prior to R2019a	Block Name from R2019a	Merger
Wye-Wye Transformer	Two-Winding Transformer (Three-Phase)	Delta-Delta Transformer Wye-Delta1 Transformer Wye-Delta11 Transformer

Compatibility Considerations

MATLAB code generates an error if it refers to a block within a library by an obsolete block name.

For example, the Single-Phase Switch block has been renamed as the SPST Switch block. The Single-Phase Switch block remains in the Switches & Breakers library.

Suppose an existing model named **modelName** contains a Single-Phase Switch block. When you open the model using the R2019a version of Simscape Electrical, the block is still named **Single-Phase Switch**. A function that calls the block in the model as an argument does not generate an error if it uses this syntax:

```
functionName('modelName/Single-Phase Switch','argument2',...,'argumentX')
```

However, code generates an error if it uses a function to add a Single-Phase Switch from the Switches & Breakers library, or in any other way changes the Single-Phase Switch block that is in the library by using this syntax:

```
functionName('Switches & Breakers/Single-Phase Switch','argument2',...,'argumentX')
```

If your code generates an error, it could contain an obsolete name as an argument in a function for adding or changing a block that is in a library. Some functions that are commonly used to manipulate blocks and block properties are:

- add_block
- set_param
- get_param

Function Name Changes: Functions renamed to ee_functionName

Simscape Electrical function names are updated from pe_functionName and elec_functionName to ee_functionName. The pe and elec functions are still available, but are set for removal in a future release.

Function Name Changes

Prior to R2019a	From R2019a
<code>elec_calculateFluxPartialDerivatives</code>	<code>ee_calculateFluxPartialDerivatives</code>
<code>elec_generateIdealPMSMfluxData</code>	<code>ee_generateIdealPMSMfluxData</code>
<code>elec_getEfficiency</code>	<code>ee_getEfficiency</code>
<code>elec_getNodeDvDtSummary</code>	<code>ee_getNodeDvDtSummary</code>
<code>elec_getNodeDvDtTimeSeries</code>	<code>ee_getNodeDvDtTimeSeries</code>
<code>elec_getPowerLossSummary</code>	<code>ee_getPowerLossSummary</code>
<code>elec_getPowerLossTimeSeries</code>	<code>ee_getPowerLossTimeSeries</code>
<code>pe_calculateThdPercent</code>	<code>ee_calculateThdPercent</code>
<code>pe_getEfficiency</code>	<code>ee_getEfficiency</code>
<code>pe_getHarmonics</code>	<code>ee_getHarmonics</code>
<code>pe_getPowerLossSummary</code>	<code>ee_getPowerLossSummary</code>
<code>pe_getPowerLossTimeSeries</code>	<code>ee_getPowerLossTimeSeries</code>
<code>pe_plotHarmonics</code>	<code>ee_plotHarmonics</code>

Example Model Name Changes: Example models renamed to `ee_modelName`

Simscape Electrical example model names are updated from `pe_modelName` and `elec_modelName` to `ee_modelName`. For each model, the simulation data log (simlog) is renamed to agree with the new model name.

Compatibility Considerations

MATLAB code generates an error if it:

- Uses an obsolete model name as an argument for any of function that loads, opens, simulates, or in any way changes the model
- References the obsolete simlog name to extract or explore simulation data.

Three-Phase Electrical Domain Changes: The three-phase electrical domain is renamed and moved to the Simscape foundation package

The three-phase electrical domain is renamed from `pe.electrical.three_phase.electrical` to `foundation.electrical.three_phase`. The domain is moved from Simscape Electrical package to the Simscape package.

Compatibility Considerations

A custom Simscape language file that uses `pe.electrical.three_phase.electrical` can not connect to any built-in three-phase blocks until the node domain is changed to `foundation.electrical.three_phase` and the component is rebuilt or updated.

Featured Examples

New examples in this release are:

- Frequency-Dependent Transmission Line— See how a frequency-dependent transmission line model compares to a classic pi-section transmission line model.
- Import IPMSM Flux Linkage Data from Motor-CAD — Import a motor design from Motor-CAD into a Simscape™ simulation.
- Load-Side Converter Control — Control RMS voltage in a load-side converter.
- PMSM Position Control — Control rotor position in a PMSM-based electrical drive.
- Power Factor Correction for CCM Boost Converter — Correct power factor by using a power factor correction (PFC) preconverter.
- Solar Panel Parameterization Validation — Validate a datasheet-parameterized solar array using current and power output data.
- Three-Phase PMSM Traction Drive — Tune a PID controller for an FEM-Parameterized PMSM.
- Vienna Rectifier Control — Control a Vienna rectifier using space-vector modulation.

Specialized Power Systems

Robust Discrete Solver: New powergui option simplifies advanced simulation settings

The robust discrete solver lets you simulate models that contain certain machine and transformer blocks without adding a parasitic load. The solver calculates and specifies the values for the advanced simulation settings.

To use the robust discrete solver option, select these settings for the powergui block:

- 1 In the **Solver** settings, for the **Simulation** parameter, select **Discrete**.
- 2 In the **Preferences** settings, select the **Automatically handle the Discrete solver and Advanced tab solver settings of blocks** option.

CCCV Battery Charger Block: Model a constant-current constant-voltage battery charger device

The CCCV Battery Charger block implements a generic smart battery charger. The model allows you to specify temperatures that effect the charge rate of the battery.

Autotuning Option for Electric Drive Blocks: AC3, AC4, AC6, and AC7 electric drive blocks can calculate PID control parameters

These electric drive blocks can determine the proportional and integral gain of the speed and flux controller from response time, damping, and bandwidth ratio of the desired loop specifications.

- Field-Oriented Control Induction Motor Drive
- DTC Induction Motor Drive
- PM Synchronous Motor Drive
- Brushless DC Motor Drive

To use the autotuning option, in the electric drive **Controller** settings:

- 1 Click **Show Autotuning Control**.
- 2 Enter the speed loop specifications.
- 3 Click **Calculate PI regulators gains**.

Sensorless Speed Estimation for AC Drive Blocks: AC3 and AC4 electric drive blocks can estimate rotational velocity

Specify a sensorless speed estimation measurement for the Field-Oriented Control Induction Motor Drive block or the DTC Induction Motor Drive block. The drive blocks estimate the motor speed from terminal voltages and currents by applying the model referencing adaptive system technique.

To use speed-estimation option, in the drive block **Controller** settings, select **Set sensorless**.

Independent Simulation Type Selection: powergui solver settings are not inherited from Simulink automatic solver settings

In R2019a, control of the settings for powergui blocks is independent from the Simulink solver settings for the model. When you select **auto (Automatic solver selection)**, Simulink no longer manages or disables the solver settings for the powergui blocks in that model.

Compatibility Considerations

If you open an existing model that has the Simulink **auto (Automatic solver selection)** solver mode selected, the powergui settings do not automatically revert to the values that you had selected before you opted to use the Simulink **auto (Automatic solver selection)** solver mode. However, you can manually change the powergui settings to the values that you selected before you opted to use the Simulink **auto (Automatic solver selection)** solver mode.

R2018b

Version: 7.0

New Features

Bug Fixes

Compatibility Considerations

Simscape Electronics and Simscape Power Systems combined into Simscape Electrical

Simscape Electrical is a new product that includes the modeling, simulation, and analysis technologies previously contained in Simscape Electronics™ (formerly SimElectronics®) and Simscape Power Systems™ (formerly SimPowerSystems™).

Find the top-level Simscape Electrical block library, now named **Electrical**, under **Simscape** in the Simulink Library Browser. It contains three sublibraries: **Electronics and Mechatronics, Power Systems**, and **Specialized Power Systems**. To open the top level-block library, at the MATLAB command prompt, enter `simscapeelectrical`.

To access release notes for prior releases of Simscape Electronics and Simscape Power Systems, see:

- Simscape Electronics Release Notes
- Simscape Power Systems Release Notes

Electronics and Mechatronics

SPICE Conversion Assistant: Convert SPICE models to Simscape components

The new SPICE conversion assistant allows you to convert SPICE netlist files into equivalent Simscape component files. For more information, see [Converting a SPICE Netlist to Simscape Blocks](#).

FEM-Parameterized PMSM Flux Parameterization: Specify flux linkage in polar or Cartesian coordinates

The FEM-Parameterized PMSM block now has additional parameterization options:

- You can use polar coordinates, rather than i_d and i_q , to tabulate fluxes
- The block accepts flux tabulation options used by Motor-CAD, as well as tabulated iron losses

Servomotor Block Loss Parameterization: Tabulate losses and efficiency as a function of speed, torque, and DC supply voltage

The Servomotor block now has additional parameterization options that let you tabulate losses and efficiency as a function of speed, torque, and DC supply voltage. Previously, you could tabulate losses and efficiency only as a function of speed and torque. See the block reference page for details.

Battery Characteristics Visualization: Plot voltage-charge characteristics for battery model parameter values

A new quick plot feature lets you visualize the voltage-charge characteristics for the battery model parameter values. To plot the characteristics, right-click a Battery or Battery (Table-Based) block and, from the context menu, select **Electrical > Basic characteristics**. The software automatically computes a set of bias conditions, based on the block parameter values, and opens a figure window containing a plot of no-load voltage versus the state-of-charge (SOC) for the block. For more information, see [Plot Basic Characteristics for Battery Blocks](#).

Peltier Device Block: Model conversion between electrical and thermal energy

The Peltier Device is a new block in the Sources library that lets you convert electrical energy into thermal energy and vice-versa.

elec_getNodeDvDtSummary and elec_getNodeDvDtTimeSeries Functions: Calculate derivatives of terminal voltages with respect to time

Checking terminal voltage derivatives with respect to time (dv/dt) helps ensure that all devices operate within their safe operating areas. Two new functions let you calculate voltage derivatives, based on logged simulation data, for block ports (terminals) that belong to the electrical domain:

- The `elec_getNodeDvDtSummary` function returns a three-column MATLAB table. The first column lists the applicable logging nodes, the second column lists the corresponding electrical terminals, and the third column lists the maximum absolute value of dv/dt for each terminal, in V/s.
- The `elec_getNodeDvDtTimeSeries` function returns a four-column MATLAB table. The first column lists the applicable logging nodes and the second column lists the corresponding electrical terminals. The third and fourth columns list the time-series data of terminal voltages, in V, and corresponding dv/dt values, in V/s, for these electrical terminals.

To use these functions, you have to enable simulation data logging and run the simulation. For more information, see [Data Logging](#).

Featured Examples

New examples in this release are:

- Use of Peltier Device as Thermoelectric Cooler
- Conducted Emission of a Buck Converter

Power Systems

Single-Phase Permanent Magnet Synchronous Motor Block: Model a single-phase PMSM with a squirrel-cage rotor

You can parameterize the Single-Phase Permanent Magnet Synchronous Motor (PMSM) block by specifying the flux linkage or the back electromotive force (BEMF) constant.

Multiphase Switched Reluctance Machines: Model low-current four-phase and five-phase SRMs

The Four-Phase Switched Reluctance Machine and Five-Phase Switched Reluctance Machine blocks represent electric motors that are driven by magnetic-reluctance torque. As is typical for reluctance machines, power is delivered to the stator rather than to the rotor.

You can parameterize either switched reluctance machine (SRM) block by specifying the saturated flux linkage, aligned inductance, and unaligned inductance or by specifying the current and angle vectors and the flux linkage matrix.

For examples that include these multiphase switched reluctance machines, see:

- Four-Phase Switched Reluctance Machine Control
- Five-Phase Switched Reluctance Machine Control

One-Quadrant Chopper Block: Convert from fixed to variable DC voltage bidirectionally

The One-Quadrant Chopper block is capable of bidirectional power flow between two connected electrical networks.

For an example that includes the One-Quadrant Chopper block, see One-Quadrant Chopper Control.

Average-Value Converters: Model DC-DC semiconductor converters that are suitable for real-time simulation

The Average-Value Chopper and Average-Value DC-DC Converter blocks allow you to convert DC voltages without switching. The relatively low computational cost of average-value converters makes them more suitable for real-time simulation than high-frequency semiconductor converter models.

For examples that include these average-value converter blocks, see:

- Average-Value Chopper Control
- Average-Value DC-DC Converter Control

Run-Time Parameter Support for All Machine Blocks: Speed up simulation tasks and modify component parameter values without regenerating C code

You can now modify certain block parameters for all electric machine blocks between simulation runs without regenerating C code or triggering the diagram update.

For more information, see Run-Time Parameters.

Single-Phase Asynchronous Machine Blocks: Model a single-phase ASM using fundamental or fundamental SI parameterization

Both the Single-Phase Asynchronous Machine (fundamental) and Single-Phase Asynchronous Machine (fundamental, SI) blocks represent a single-phase asynchronous machine with a squirrel cage rotor that you parameterize using fundamental per-unit or SI parameters, respectively. Choose between these four variants for either block:

- Split-phase
- Capacitor-start
- Capacitor-start-capacitor-run
- Main and auxiliary windings

For examples that include these single-phase ASM blocks, see:

- Single-Phase Asynchronous Machine Direct Torque Control
- Single-Phase Asynchronous Machine Field-Oriented Control

Asynchronous Machine Saturation: Include magnetic saturation in three-phase ASMs using open circuit lookup tables

Model magnetic saturation using lookup tables of per-unit no-load stator current saturation and the per-unit terminal voltage saturation data for these asynchronous machine (ASM) blocks:

- Asynchronous Machine Squirrel Cage (fundamental)
- Asynchronous Machine Squirrel Cage (fundamental, SI)
- Asynchronous Machine Wound Rotor (fundamental)
- Asynchronous Machine Wound Rotor (fundamental, SI)

To plot saturation data for an ASM block in a MATLAB figure window, right-click the block, select the **Electrical** menu on the block context menu, and then choose one of these actions:

- **Plot Open-Circuit Saturation** — Plots terminal voltage versus no-load stator current. The plot contains three traces:
 - Unsaturated
 - Saturated
 - Derived
- **Plot Saturation Factor** — Plots saturation factor applied to magnetic inductance versus magnetic flux linkage.

- **Plot Saturated Inductance** — Plots magnetizing inductance versus per-unit magnetic flux linkage.

If you use the saturation mode, the **Magnetizing inductance, L_m (pu)** parameter (for fundamental blocks) or the **Magnetizing reactance, X_m** parameter (for fundamental, SI blocks) is hidden because the block computes the value based on the saturation curve.

Double-Squirrel Cage Asynchronous Machines: Specify a single or double cage for ASM squirrel cage blocks

You can now specify a single or double cage for these Asynchronous Machine (ASM) Squirrel Cage blocks.

- Asynchronous Machine Squirrel Cage (fundamental)
- Asynchronous Machine Squirrel Cage (fundamental, SI)

When you model a double cage, you can specify separate referred rotor resistance and leakage inductance for each cage.

Synchronous Machine Rotor Angle: Define the rotor axis alignment for synchronous machine blocks

You can now define the reference point for the rotor angle measurement in these synchronous machine blocks:

- Synchronous Machine Model 2.1 (fundamental)
- Synchronous Machine Model 2.1 (standard)
- Synchronous Machine Round Rotor (fundamental)
- Synchronous Machine Round Rotor (standard)
- Synchronous Machine Salient Pole (fundamental)
- Synchronous Machine Salient Pole (standard)

The default value for the **Rotor angle definition** is Angle between the a-phase magnetic axis and the d-axis. When you select this value, the rotor *d*-axis and stator *a*-phase magnetic axis are aligned when the rotor angle is zero. The other value you can choose for this parameter is Angle between the a-phase magnetic axis and the q-axis. When you select this value, the rotor *q*-axis and stator *a*-phase magnetic axis are aligned when the rotor angle is zero.

Synchronous Machine Block Accuracy Improvement: SM blocks that use standard parameters and the SM field circuit block return more accurate results

Due to improved mapping of mask parameters to model coefficients, in certain configurations, the simulation results from models that contain these synchronous machine blocks are more accurate in R2018b:

- Synchronous Machine Model 2.1 (standard)
- Synchronous Machine Round Rotor (standard)

- Synchronous Machine Salient Pole (standard)
- Synchronous Machine Field Circuit (pu)

Machine Plotting and Display Options: Perform plotting and display actions using the Electrical menu

In previous releases, you could perform plotting and display actions for machine blocks using the **Power Systems** menu on the block context menu. Now, use the **Electrical** menu on the block context menu to perform those same actions. For more information, see Plotting and Display Options for Asynchronous and Synchronous Machines.

Controlled Current Source (Three-Phase) Block: Control the current loop of a cascading control system

Use the Controlled Current Source (Three-Phase) block to control the output current of a current loop in a cascading control system or to represent a low-fidelity converter without modeling switches.

Expanded Control Library: Speed up modeling by using prebuilt and documented algorithm components

Save time deriving, implementing, testing, debugging, and documenting algorithm models by using blocks from the expanded Control library. The blocks are Simulink blocks that are modular and decoupled, customizable, and compatible with Embedded Coder. Each block provides open access to the implementation source code.

To access the new blocks in the Simulink Library Browser, select, **Electrical > Power Systems > Control**, and then:

- **ASM Control** — For these single-phase ASM control blocks:
 - Single-Phase ASM Direct Torque Control — For an example that includes this block, see Single-Phase Asynchronous Machine Direct Torque Control.
 - Single-Phase ASM Field-Oriented Control — For an example that includes this block, see Single-Phase Asynchronous Machine Field-Oriented Control.
- **SM Control** — For the SM PSS1A block, which models a power system stabilizer with parameters that can account for the low-frequency effect of high-frequency torsional filters or shape the gain and phase characteristics of the stabilizer.
- **General Control** — For these control blocks:
 - Change Detector — Detect a change in the Boolean input.
 - Counter — Implement a fixed-time-period counter.
 - Fourier Analysis — Obtain the magnitude and angle of the input signal for a specified harmonic.
 - Monostable Flip-Flop — Generate a single pulse of a specified duration in response to an external trigger.
 - Moving Average — Calculate the average value of the input over a moving window.
 - On-Off Delay — Add a time delay in response to a detected transition in the input signal.

- Second-Order Filter — Implement a low-pass, high-pass, band-pass, or band-stop second-order filter.
- Second-Order Low-Pass Filter (Discrete or Continuous) — Implement an IEEE Std 421.5 second-order low-pass filter.
- Serial-In Parallel-Out Shift Register — Obtain a vector of last N samples of the input signals.
- Set-Reset Flip-Flop — Implement a bistable.
- Signal Sample and Hold — Sample and hold the input signal.
- Variable-Frequency Second-Order Filter — Implement a low-pass, high-pass, band-pass or band-stop second-order filter with variable frequency.

Battery Characteristics Visualization: Plot voltage-charge characteristics for battery model parameter values

A new quick-plot feature lets you visualize the voltage-charge characteristics for the battery model parameter values. To plot the characteristics, right-click a Battery or Battery (Table-Based) block and, from the context menu, select **Electrical > Basic characteristics**. The software automatically computes a set of bias conditions based on the block parameter values, and opens a figure window containing a plot of no-load voltage versus the state-of-charge (SOC) for the block.

Block Name Changes: Blocks names disambiguated from identically named blocks in the Simscape Electrical Electronics and Mechatronics library

Blocks names that are identical to the names of blocks in the Simscape Electrical Electronics and Mechatronics libraries are changed in R2018b.

Block Name Changes

Library Path	Name Prior to R2018b	New Name
Simscape > Electrical > Power Systems > Passive Devices > Fundamental Components	Transmission Line	Transmission Line (Three-Phase)
Simscape > Electrical > Power Systems > Semiconductors > Fundamental Components	Diode	Diode (Piecewise Linear)
	Thyristor	Thyristor (Piecewise Linear)
Simscape > Electrical > Power Systems > Sources	Current Source	Current Source (Three-Phase)
	Voltage Source	Voltage Source (Three-Phase)

Compatibility Considerations

To prevent a script that contains the previous name of a block from producing an error, update the block names in your code.

HDL Code Generation from Simscape Electrical Power Systems Models: Convert models to HDL code for simulation on FPGA devices

If you have an HDL Coder™ license, you can use the Simscape HDL Advisor advisor to deploy a linear or switched linear plant model developed using Simscape Electrical blocks to a target FPGA. To generate code using the Simscape HDL Advisor:

- 1** Configure the Power Systems model for conversion.
- 2** Convert the Power Systems model to an HDL code-compatible implementation model.
- 3** Generate HDL code from the implementation model.

For more information, see Real-Time Simulation.

Featured Examples

New examples in this release are:

- Average-Value Chopper Control
- Average-Value DC-DC Converter Control
- DC Motor Control (Lead-Lag)
- DC Motor Control (RST)
- DC Motor Control (Smith Predictor)
- DC Motor Control (State-Feedback and Observer)
- Five-Phase Switched Reluctance Machine Control
- Four-Phase Switched Reluctance Machine Control
- IPMSM Outer Loop Controller Evaluation
- One-Quadrant Chopper Control
- PMSM Parameterization from Datasheet
- PMSM Parameterization from Measurements
- Single-Phase Asynchronous Machine Direct Torque Control
- Single-Phase Asynchronous Machine Field-Oriented Control
- Vienna Rectifier

Specialized Power Systems

SVPWM Generator (3-Level) Block: Generate pulses for three-phase three-level neutral-point-clamped converters

The SVPWM Generator (3-Level) block outputs 12 pulses that it generates using the space vector pulse width modulation (SVPWM) technique. A proportional regulator controls the neutral point voltage deviation of the NPC converter based on the DC voltage references and the DC current flowing in or out of the DC link.

Featured Example

The Three-Level NPC Inverter Using Space-Vector PWM with Neutral-Point Voltage Control example shows how to operate a 2-MVA, 3-Level NPC inverter using the Space Vector Pulse-Width-Modulation (SVPWM) technique with neutral point voltage control.

